

Sparse linear models in high-dimensions

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Econometrics Reading Group

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Problem Formulation

Different Sparsity Models

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Sparse linear models in high-dimensions

- The goal of this chapter is to provide an overview of the most popular used *shrinkage estimators* in the machine learning literature and how are they useful in the context of *linear regression* models from the perspective of econometrics analysis.
- Shrinkage estimators provide a feasible approach to potentially identify *relevant variables* from a *large pool* of covariates.
- So our fundamental problem is a *linear model* with a large parameter vector that *potentially* contains many zeros (i.e., sparsity).
- The main assumption is that, while the number of covariates is large, perhaps much larger than the number of observations, the number of *associated non-zero* coefficients is relatively small.
- We can extend this framework even for nonparametric models (e.g., kernel ridge regressions).
- **Applications:** IVs from a many potentially weak instruments.

- Let $\theta^* \in \mathbb{R}^d$ be an *unknown vector*, referred to as the regression vector.
- Suppose that we observe a vector $y \in \mathbb{R}^n$ and a matrix $\mathbf{X} \in \mathbb{R}^{n \times d}$ that are linked via the standard linear model

$$y = \mathbf{X}\theta^* + w$$

where $w \in \mathbb{R}^n$ is a vector of noise variables.

- This model can also be written in a scalarized form: for each index $i = 1, 2, \dots, n$, we have $y_i = \langle x_i, \theta^* \rangle + w_i$, where $x_i^T \in \mathbb{R}^d$ is the i -th row of \mathbf{X} , and y_i and w_i are (respectively) the i -th entries of the vectors y and w .
- The quantity $\langle x_i, \theta^* \rangle := \sum_{j=1}^d x_{ij}\theta_j^*$ denotes the usual *Euclidean inner product* between the vector $x_i \in \mathbb{R}^d$ of predictors (or covariates), and the regression vector $\theta^* \in \mathbb{R}^d$.
- Thus, each response y_i is a noisy version of a linear combination of d covariates.

- As we know when $d > n$ it's impossible to obtain any meaningful estimates of θ^* unless we impose a *low dimensional structure*.
- **Key concept:** Sparsity
- Let us define the *support set* of θ^* as

$$S(\theta^*) := \{j \in \{1, 2, \dots, d\} \mid \theta_j^* \neq 0\},$$

- This set has cardinality $s := |S(\theta^*)|$ *substantially smaller* than d .
- Assuming that the model is exactly supported on s coefficients may be overly restrictive, in which case it is also useful to consider various relaxations of hard sparsity, which leads to the notion of weak sparsity.
- Roughly speaking, a vector θ^* is *weakly sparse* if it can be *closely approximated* by a *sparse vector*.

- There are different ways in which to formalize such an idea, one way being via the ℓ_q - "norms".
- For a parameter q and radius $R_q > 0$, consider the set

$$\mathbb{B}_q(R_q) = \left\{ \theta \in \mathbb{R}^d \mid \sum_{j=1}^d |\theta_j|^q \leq R_q \right\}.$$

- It is known as the ℓ_q -ball of radius R_q .

Shrinkage Estimators and Regularizers

- The *size* of a parameter vector θ is the *number of elements* in the vector and the *length* of θ is the length of the vector as measured by an assigned *norm*.
- The ℓ_q norm of a vector $\theta = (\theta_1, \dots, \theta_d)'$ denoted by the notation, $\|\theta\|_q$, is defined as

$$\|\theta\|_q = \left(\sum_{j=1}^d |\theta_j|^q \right)^{1/q} \quad q > 0,$$

where $|\theta|$ denotes the absolute value of θ .

- When $q = 2$, the ℓ_q norm is known as the *Euclidean Norm*, or *Euclidean Distance*

Example

Let $\theta = (\theta_1, \theta_2)$, then the ℓ_2 Euclidean norm of θ is $\|\theta\|_2 = \sqrt{|\theta_1|^2 + |\theta_2|^2}$.

- The idea of a shrinkage estimator is to impose a *restriction on the length* of the estimated parameter vector $\hat{\theta}$.
- In other words, the idea is to *shrink* the parameter vector in order to identify the 0 elements in θ .
- This can be framed as the following optimization problem:

$$\hat{\theta} = \underset{\theta \in \Theta}{\operatorname{argmin}} \mathcal{L}(\theta; \mathbf{y}, \mathbf{X})$$

$$\text{s.t. } \operatorname{pen}(\theta) \leq c,$$

where $\mathcal{L}(\theta; \mathbf{y}, \mathbf{X})$ is the loss function, and $\operatorname{pen}(\theta)$ is a *penalty* term or *regularizer* for any $c > 0$.

- Different definitions of $\operatorname{pen}(\theta)$ lead to different shrinkage estimators.
- Let's write the previous optimization problem in its Lagrange form

$$\hat{\theta} = \underset{\theta \in \Theta}{\operatorname{argmin}} \mathcal{L}(\theta; \mathbf{y}, \mathbf{X}) + \lambda \operatorname{pen}(\theta)$$

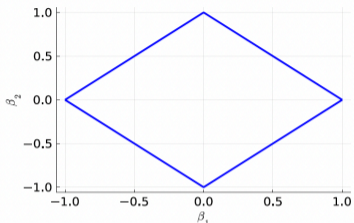
- A interesting class of regularizers is called the *Bridge estimator* as defined by Frank and Friedman (1993), which proposed the following regularizer in the equation

$$\text{pen}(\theta; q) = \|\theta\|_q^q = \sum_{j=1}^d |\theta_j|^q, \quad q \in \mathbb{R}^+.$$

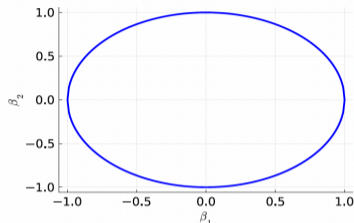
The Bridge estimator encompasses at least two shrinkage estimators as special cases.

- When $q = 1$, the Bridge estimator becomes the *Least Absolute Shrinkage and Selection Operator* (LASSO) as proposed by Tibshirani (1996)
- When $q = 2$, the Bridge estimator becomes the *Ridge estimator* as defined by Hoerl and Kennard (1970b, 1970a).
- We can define further a linear combination of LASSO and Ridge, which is called *Elastic Net*:

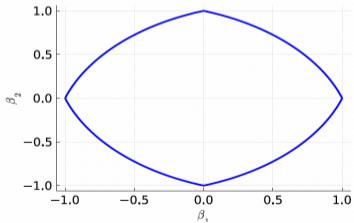
$$\text{pen}(\theta; \alpha) = \sum_{j=1}^d \alpha |\theta_j| + (1 - \alpha) |\theta_j|^2$$



(a) LASSO



(b) Ridge



(c) Elastic Net

- An advantage of the ℓ_1 norm i.e., LASSO, is that it can produce estimates with exactly zero values, i.e., elements in $\hat{\theta}$ can be exactly zero. This means we will have *corner solutions*.
- While the ℓ_2 norm, i.e., Ridge, does not usually produce estimates with values that equal exactly 0. Ridge contour does not have the *sharp corners*.
- However, the Ridge does have a *computational advantage* over other variations of the Bridge estimator. \implies **Closed Form Solution**

Proposition (Closed Form Solution of Ridge)

When $q = 2$ and $\mathcal{L}(\theta; \mathbf{y}, \mathbf{X}) = (\mathbf{y} - \mathbf{X}\theta)^\top (\mathbf{y} - \mathbf{X}\theta)$ i.e., mean-square loss function, there is a closed form solution, namely $\hat{\theta}_{\text{Ridge}} = (\mathbf{X}^\top \mathbf{X} + \lambda \mathbf{I})^{-1} \mathbf{X}^\top \mathbf{y}$

- We can generalize this even for functions using *Kernel Ridge Regressions* and *RKHS* learning theory in nonparametric estimation! (more on this in 2 chapters)

$$f^* = \operatorname{argmin}_{f \in \mathcal{H}} \left(\frac{1}{n} \sum_{i=1}^n (y_i - f(x_i))^2 + \lambda \|f\|_{\mathcal{H}}^2 \right)$$

The Regularization Bias

- Let's focus in Lasso in this section.
- Denote by $\mathcal{L}(\theta) = n^{-1} \sum_{i=1}^n (Y_i - X_i^\top \theta)^2$ the mean-square loss function.
- The Lasso estimator is defined as:

$$\hat{\theta} \in \underset{\theta \in \mathbb{R}^d}{\operatorname{argmin}} \mathcal{L}(\theta) + \lambda \|\theta\|_1.$$

- The Lasso minimizes the sum of the empirical mean-square loss and a penalty or regularization term $\lambda \|\theta\|_1$.
- Notice that the solution to previous program is not necessarily unique.
- λ sets the trade-off between *fit* and *sparsity*
- **Caution:** In presence of a high-dimensional θ_0 (true parameter) for which the *sparsity assumption* is not assumed to hold, using the Lasso estimator is not a good idea.

- Lasso has a cousin called *Post-Lasso*.
- This algorithm has been studied at Belloni and Chernozhukov (2011) and Belloni and Chernozhukov (2013)
- It is a *two-step estimator* in which a second step is added to the Lasso procedure in order to remove the bias that comes from shrinkage.
- That second step consists in running an OLS regression using only the covariates associated with a non-zero coefficient in the Lasso step.
 1. Run the Lasso regression and denote $\hat{s}(\theta)$ the estimator of the *support set* of θ , i.e., the non-zero Lasso coefficients.
 2. Run an OLS regression including only the covariates corresponding to the *non-zero coefficients* in $\hat{s}(\theta)$ from above.

- A natural appeal of the Post-Lasso estimator is that it is a powerful tool for variable selection.
- However, we have to discuss the *regularization bias* which is nothing more than an *omitted variable bias* arising from the same mechanism described previously.

Remark

Model selection and estimation cannot be achieved optimally at the same time.

- Yang (2005) shows that for any model selection procedure to be consistent, it must behave *sub-optimally* for estimating the regression function and vice-versa.

Example (Linear model with high-dimensional controls)

Consider the iid sequence of random variables $(Y_i, D_i, X_i)_{i=1}^n$ such that:

$$Y_i = D_i\theta_0 + X_i^\top \beta_0 + \varepsilon_i,$$

with ε_i such that $\mathbb{E}[\varepsilon] = 0$, $\mathbb{E}[\varepsilon]^2 = \sigma^2 < \infty$ and $\varepsilon_i \perp (D_i, X_i)$. θ_0 capture the treatment effect of a binary treatment $D_i \in \{0, 1\}$. X_i is of dimension $d > 1$. d is allowed to be much larger than n and to grow with n . Denote by $\mu_d := \mathbb{E}(X | D = d)$ for $d \in \{0, 1\}$ and $\pi_0 := \mathbb{E}[D]$.

- In this example we are interested in estimate *treatment effect* θ_0
- So β_0 is just a *nuisance parameter*.

Two-step estimator:

1. Run a *Lasso regression* of Y on D and \mathbf{X} , forcing D to remain in the model by excluding θ_0 from the penalty part in the Lasso. Exclude all the elements in \mathbf{X} that correspond to a zero coefficients $\hat{\beta}^{\text{lasso}}$
2. Run an *OLS regression* of Y on D and the *set of selected* \mathbf{X} to obtain the post-selection estimator $\hat{\theta}^{\text{post}}$

- Denote $\hat{\beta}$ the corresponding estimator for β_0 obtained in step 2. Notice that for $j \in \{1, \dots, d\}$, if $\hat{\beta}_j^{\text{lasso}} = 0$ then $\hat{\beta}_j = 0$.
- Also denote by $\hat{\pi} := n^{-1} \sum_{i=1}^n D_i$. Therefore,

$$\hat{\theta} := \frac{\frac{1}{n} \sum_{i=1}^n D_i (Y_i - \mathbf{X}_i^{\top} \hat{\beta})}{\hat{\pi}} = \frac{1}{n_1} \sum_{D_i=1} (Y_i - \mathbf{X}_i^{\top} \hat{\beta}),$$

where $n_d := \sum_{i=1}^n \mathbf{1}\{D_i = d\}$, $d \in \{0, 1\}$.

Lemma

Under the previous linear model, if $\mu_1 \neq 0$, then $\sqrt{n} (\hat{\theta} - \theta_0) \rightarrow \infty$

Sketch of the proof: Substitute the linear model in the expression of $\hat{\theta}$ to get

$$\sqrt{n} (\hat{\theta} - \theta_0) = \hat{\pi}^{-1} \left[\frac{1}{n} \sum_{i=1}^n D_i X_i \right]^\top \sqrt{n} (\beta_0 - \hat{\beta}) + \hat{\pi}^{-1} \sqrt{n} \left[\frac{1}{n} \sum_{i=1}^n D_i \varepsilon_i \right]$$

By CLT, CMT, LLN and Slutsky

$$\begin{aligned} \left[\frac{1}{n} \sum_{i=1}^n D_i X_i \right] &\xrightarrow{p} \pi_0 \mu_1. \\ \hat{\pi}^{-1} \left[\frac{1}{\sqrt{n}} \sum_{i=1}^n D_i \varepsilon_i \right] &\xrightarrow{d} \mathcal{N} \left(0, \frac{\sigma^2}{\pi_0} \right) \end{aligned}$$

$$\left| \left[\frac{1}{n} \sum_{i=1}^n D_i X_i \right]' \sqrt{n} (\beta_0 - \hat{\beta}) \right| \approx s \sqrt{\log d} \rightarrow \infty$$

Orthogonalization

- This is the main idea in Chernozhukov et al. (2017); Belloni et al. (2017); Chernozhukov et al. (2018).
- To build the intuition, assume that the parameter of interest, θ_0 solves the equation $\mathbb{E}m(Z_i, \theta_0, \beta_0) = 0$ for some known *score function* $m(\cdot)$, a vector of observables Z_i and nuisance parameter β_0 .
- In the simplest case, think about the *score function* as the first derivative of the log-likelihood functions in the parametric case.
- From our example: $Z_i = (Y_i, D_i, X_i)$, and $m(Z_i, \theta, \beta) := (Y_i - D_i\theta - X_i^\top \beta) D_i$.
- The derivative of the estimating moment with respect to nuisance parameter is not zero:

$$\mathbb{E}\partial_\beta m(Z_i, \theta_0, \beta_0) = -\pi_0\mu_1 \neq 0.$$

Idea: Can we replace $m(\cdot)$ by another score function $\psi(\cdot)$ and use a different nuisance parameter η_0 such that

$$\mathbb{E}\partial_\eta \psi(Z_i, \theta_0, \eta_0) = 0$$

- We say that any function ψ that satisfies previous condition is an *orthogonal score* or *Neyman-Orthogonal*
- **Intuition:** The moment condition for estimating θ_0 is not affected by small perturbations around the true value of the nuisance parameter η_0 .
- Changing the estimating moment can neutralize the effect of the first step estimation and suppress the *regularization bias*.

Assumption (Orthogonal Moment Condition)

The (scalar) parameter of interest, θ_0 is given by:

$$\mathbb{E}\psi(Z_i, \theta_0, \eta_0) = 0$$

for some known real-valued function $\psi(\cdot)$ satisfying the *orthogonality condition*, a vector of observables Z_i and a high-dimensional sparse nuisance parameter η_0 such that $\|\eta_0\|_0 \leq s$.

Assumption (High-Quality Nuisance Estimation)

Let first-step estimator $\hat{\eta}$ such that with high-probability:

$$\begin{aligned}\|\hat{\eta}\|_0 &\lesssim s \\ \|\hat{\eta} - \eta_0\|_1 &\lesssim \sqrt{s^2 \log d/n} \\ \|\hat{\eta} - \eta_0\|_2 &\lesssim \sqrt{s \log d/n}\end{aligned}$$

Assumption (Affine-Quadratic Model)

The function $\psi(\cdot)$ is such that:

$$\psi(Z_i, \theta, \eta) = \Gamma_1(Z_i, \eta)\theta - \Gamma_2(Z_i, \eta)$$

where $\Gamma_j, j = 1, 2$, are functions with all their *second order derivatives* with respect to η constant over the convex parameter space of η .

The estimator we are going to consider is $\check{\theta}$ such that:

$$\frac{1}{n} \sum_{i=1}^n \psi(Z_i, \check{\theta}, \hat{\eta}) = 0.$$

Theorem (Asymptotic Normality)

The estimator $\check{\theta}$ in the affine-quadratic model and under previous assumptions:

$$\sqrt{n}(\check{\theta} - \theta_0) \xrightarrow{d} \mathcal{N}(0, \sigma_{\check{\theta}}^2), \text{ with } \sigma_{\check{\theta}}^2 := \mathbb{E}[\psi(Z_i, \tau_0, \eta_0)^2] / \mathbb{E}[\Gamma_1(Z_i, \eta_0)]^2.$$

- The Orthogonalization framework can be generalized for other ML learner algorithms.
- This is the main idea of *Double Machine Learning* (DML) (More on this in next chapters)
- DML builds on the FWL theorem to isolate the effect of interest, introducing a key idea: the use of ML models in the orthogonalization process.

1. $\hat{D} = f(X) + v$

$$\Rightarrow \tilde{D} = D - \hat{X}$$

2. $\hat{Y} = g(X) + u$

$$\Rightarrow \tilde{Y} = Y - \hat{Y}$$

3. $\tilde{Y} = \theta_0 + \theta_1 \tilde{X} + \varepsilon$

- We can define a Lasso procedure where *Neyman-Orthogonality* holds

The Double Lasso procedure:

1. We run Lasso regressions of Y_i on X_i and D_i on X_i

$$\begin{aligned}\hat{\gamma}_{YX} &= \arg \min_{\gamma \in \mathbb{R}^p} \sum_i (Y_i - \gamma^\top X_i)^2 + \lambda_1 \sum_j \hat{\psi}_j^Y |\gamma_j|, \\ \hat{\gamma}_{DX} &= \arg \min_{\gamma \in \mathbb{R}^p} \sum_i (D_i - \gamma^\top X_i)^2 + \lambda_2 \sum_j \hat{\psi}_j^D |\gamma_j|,\end{aligned}$$

where $\hat{\psi}_j$ are penalty loadings normally equal to 1. Then, we obtain the resulting residuals:

$$\begin{aligned}\check{Y}_i &= Y_i - \hat{\gamma}_{YX}^\top X_i, \\ \check{D}_i &= D_i - \hat{\gamma}_{DX}^\top X_i.\end{aligned}$$

In place of Lasso, we can use Post-Lasso or other Lasso relatives.

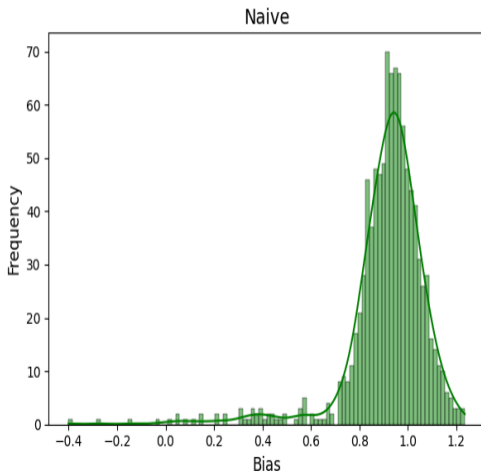
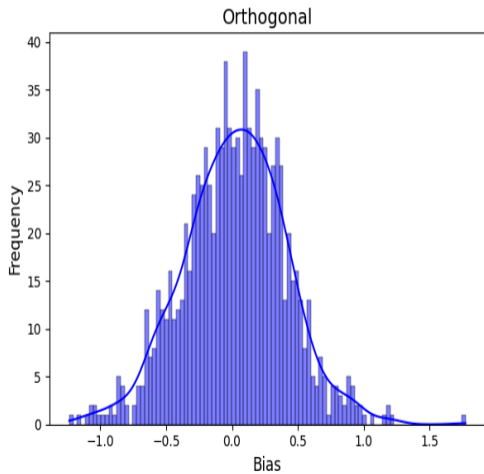
2. We run the least squares regression of \check{Y}_i on \check{D}_i to the estimator $\check{\theta}$.

We compare the performance of the *naive* (e.g., Post-Lasso) and *orthogonal* methods (e.g., Double Lasso) in a computational experiment where $d = n = 100$, $\beta_j = 1/j^2$, $\gamma_j = 1/j^2$, and

$$Y = \mathbf{1} \cdot D + \beta^\top X + \varepsilon_Y, \quad X \sim N(\mathbf{0}, I), \varepsilon_Y \sim N(0, 1)$$
$$D = \gamma^\top X + \tilde{D}, \quad \tilde{D} \sim N(0, 1)/4$$

Here the true parameter is 1.

Distribution of Estimates (Centered around Ground Truth)



```
# Initialize constants
B = 1000 # Number of iterations
n = 100 # Sample size
d = 100 # Number of features

# Sim Parameters
mean = 0
sd = 1

# Initialize arrays to store results
naive = np.zeros(B)
orthogonal = np.zeros(B)
```

```
# Iterate through B simulations
for i in tqdm(range(B)):
    # Generate parameters:
    gamma = (1 / (np.arange(1, d + 1) ** 2)).reshape(d, 1)
    beta = (1 / (np.arange(1, d + 1) ** 2)).reshape(d, 1)

    # Generate covariates / random data
    X = np.random.normal(mean, sd, n * d).reshape(n, d)
    D = (X @ gamma) + np.random.normal(mean, sd, n).reshape(n, 1) / 4

    # Generate Y using DGP
    Y = D + (X @ beta) + np.random.normal(mean, sd, n).reshape(n, 1)

    # Single selection method using rlasso
    r_lasso_estimation = hdmpy.rlasso(np.concatenate((D, X), axis=1), Y, post=True)
    coef_array = r_lasso_estimation.est['coefficients'].iloc[2:, :].to_numpy()
    SX_IDs = np.where(coef_array != 0)[0]

    # Check if any X coefficients are selected
    if sum(SX_IDs) == 0:
        # If no X coefficients are selected, regress Y on D only
        naive[i] = sm.OLS(Y, sm.add_constant(D)).fit().params[1]
    else:
        # If X coefficients are selected, regress Y on selected X and D
        X_D = np.concatenate((D, X[:, SX_IDs]), axis=1)
        naive[i] = sm.OLS(Y, sm.add_constant(X_D)).fit().params[1]

    # Double Lasso Partialling Out
    resY = hdmpy.rlasso(X, Y, post=False).est['residuals']
    resD = hdmpy.rlasso(X, D, post=False).est['residuals']
    orthogonal[i] = sm.OLS(resY, sm.add_constant(resD)).fit().params[1]
```

Thanks!

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